

VECTOR

Vermont Enhanced CORS and Transmission Of Real-time
Corrections

Network Status and Current Applications

Daniel J. Martin, National Geodetic Survey
Bill Kules, Little River Survey
Ron Tabor, Vermont Geomatics

Vermont Society of Land Surveyors
December 19, 2008

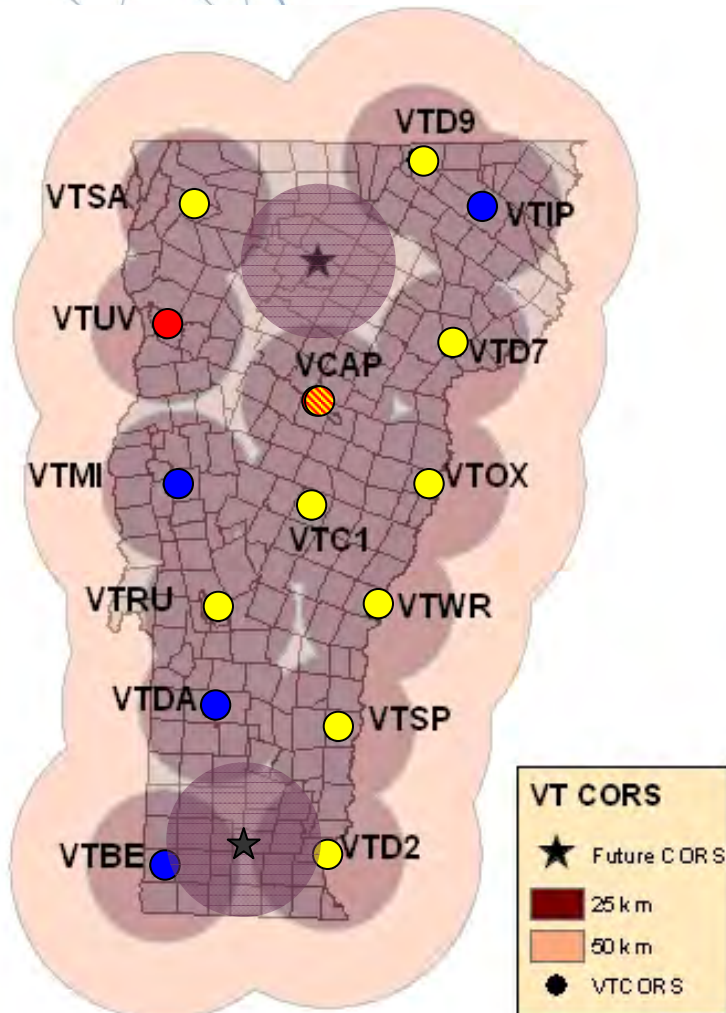


What is VECTOR??

- Network of Continuously Operating GNSS Reference Stations.
- Provides access to the National Spatial Reference System (NSRS)
- Access available for post processing (Static) and Real-time.



VECTOR Expansion



- 1996 - VCAP
- 2004 - VTUV
- 2006 – VTD2, VTSP, VTWR, VTOX, VTD7, VTD9, VTC1, VTSA, VTRU, (VCAP Upgrade)
- 2008 – VTBE, VTDA, VTMI, VTIP
- Minimum of 1 station needed to fill out network (Eden), ideally another (Dover, Stratton, Jamaica, or Wardsboro)

VECTOR

Site Criteria

- $\approx 40\text{-}50$ km spacing
- Masonry building ≤ 2 story
- Secure location
- State owned
- Clear view to sky
- Stable/dedicated power source
- High speed internet connection
- Antenna location < 100 meters from receiver location



Static Component of VECTOR

- Hourly files (1-sec)
 - DAT, RINEX v2.1 (no more SSF)
- Online for 45 days (VT-web)
- New download interface (similar to NGS UFC)
- 10 stations are National CORS
- All stations submitted to National CORS
- Preliminary coordinates derived from average of OPUS observations

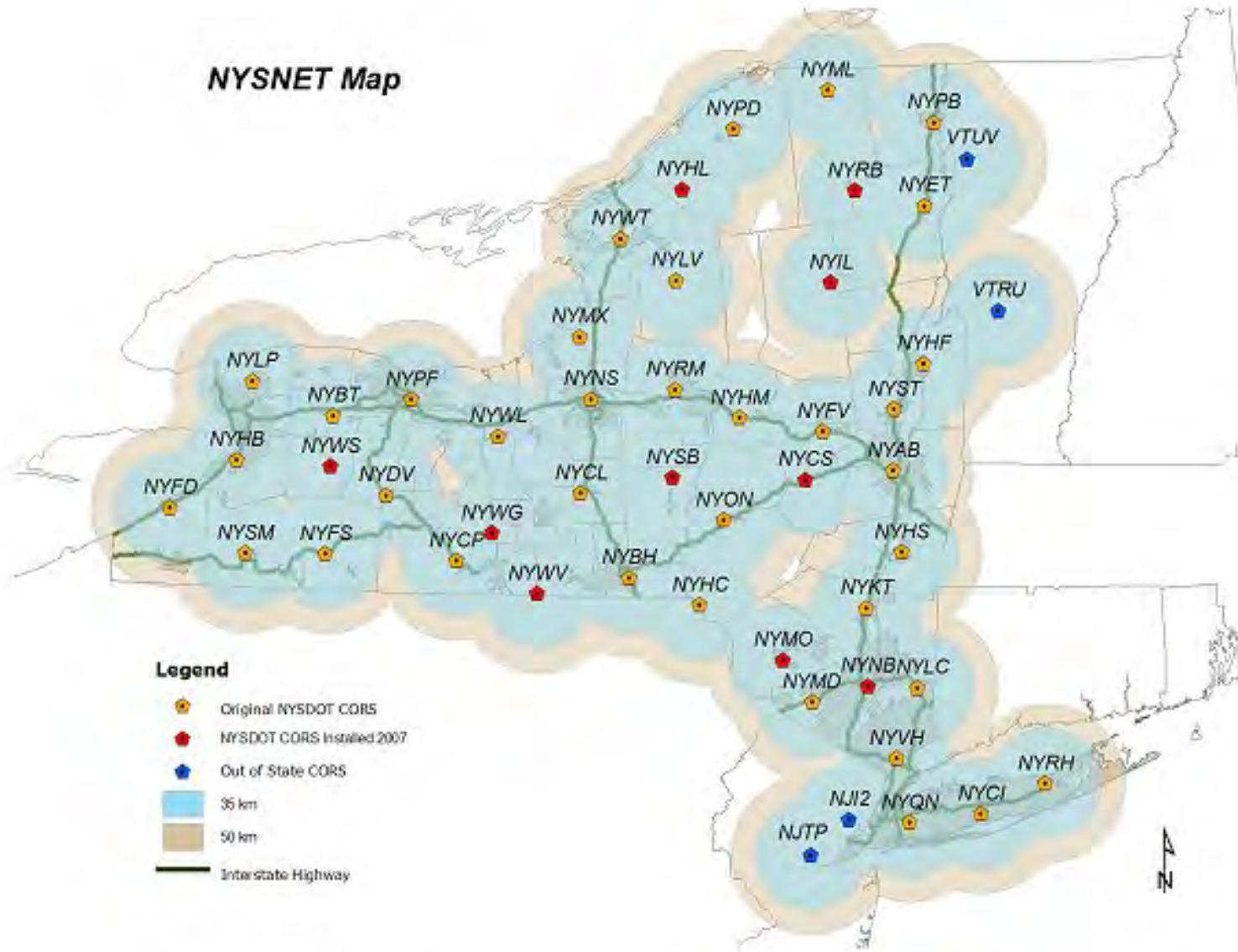


Real-time Component of VECTOR

- User registration required (form on web)
- RTK data available via IP (cell connection)
- Single baseline RTK
- User must specify which site to receive corrections from by selecting mountpoint
- Field equipment must support NTRIP (Networked Transport of RTCM via Internet Protocol)
- Data streams available in CMR+ and RTCMv2.3 formats.



NYSNET Map





Service Updates

- [2008 Subscriber / Participant Meeting Set](#)
- [Mount Point Names Change](#)

Technical Documents

- [KeyNet GPS Users Guide](#)
- [TMobil Settings For TSC2](#)
- [Audiovox TSC2 Setup](#)
- [Survey Controller ver 11.32 Configuration for Audiovox Cellular Modem Adapter Using](#)

Network Map

Station connected Tracking 5 or more satellites. Station connected Tracking less than 5 satellites. Station disconnected Tracking 0 satellites.

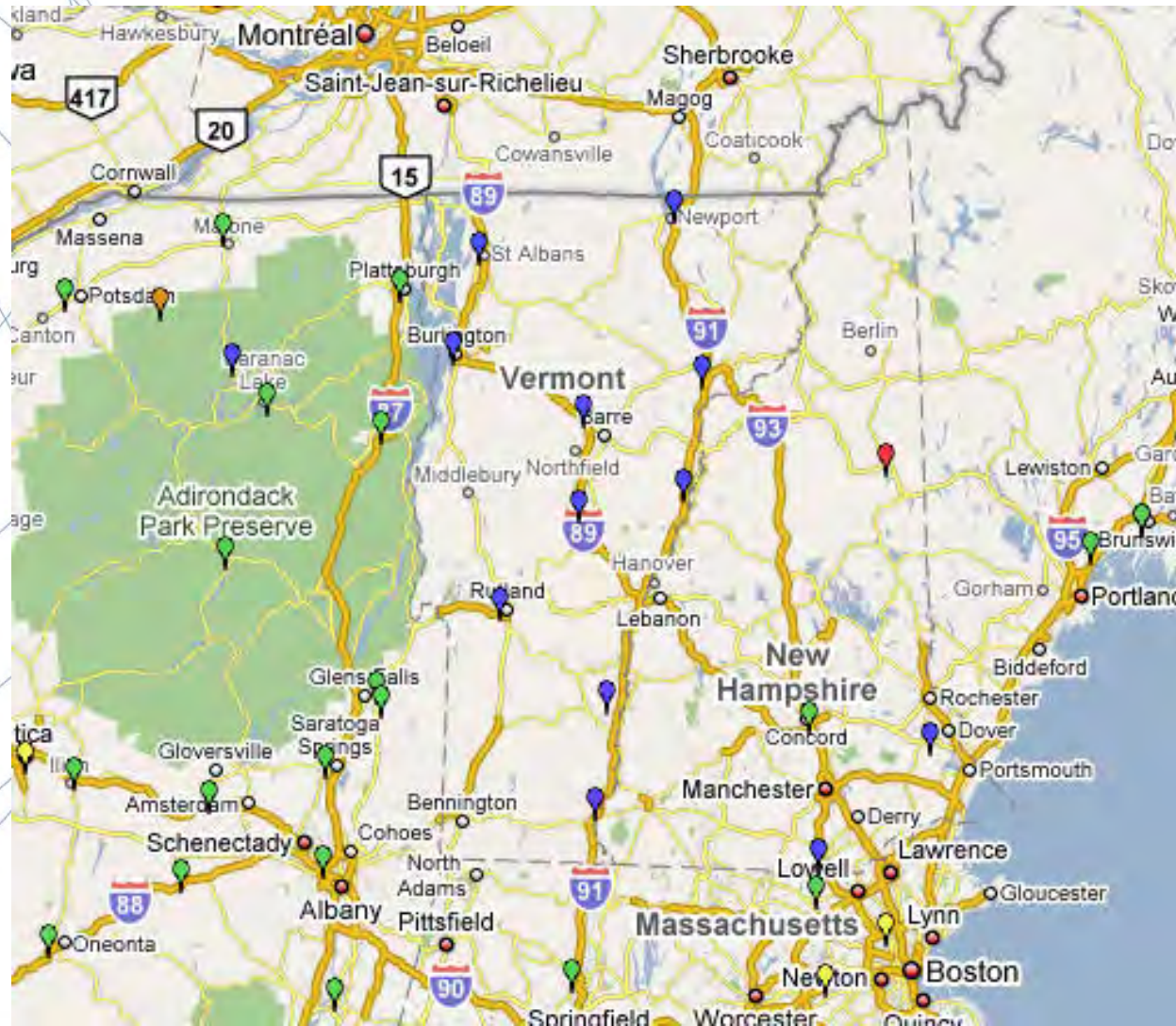
Map Satellite Hybrid Terrain

Number of Bases: 108
Current Base: VTSP
Cursor Lat/Long: 43.78695837, -72.20214844
Three Nearest Bases:
VTWR 17.94 km
VTOX 25.58 km
VTC1 36.40 km

Type an address



National CORS as of 12/08



How is VECTOR being used

- Static Download from VT and NGS Servers (web)
- Static Download from VT and NGS Servers (ftp)
- Used for OPUS and OPUS_RS Solutions
- Used for OPUS_DB
- Real-time
- Incorporated into other networks (NY, Keynet, MTS)
- Contributing to NOAA weather forecasting (PWV)
- Contributing to the computation of GLONASS orbits



What is OPUS?

- **On-Line Positioning User Service**
- **Processes Dual-Frequency (and single frequency) GPS data**
- **Global availability (masked)**
- **3 goals:**
 - **Simplicity**
 - **Consistency**
 - **Reliability**



Flavors of OPUS

- OPUS_S (Static)
 - Operational since 2001
- OPUS_RS (Rapid Static)
 - Operational since 2007
- OPUS_DB (Database)
 - Initial Operational Capability (IOC) in 2008
- OPUS_Projects (Network campaigns)
 - Beta (internal testing)
- OPUS_Mapper (L1)
 - Alpha

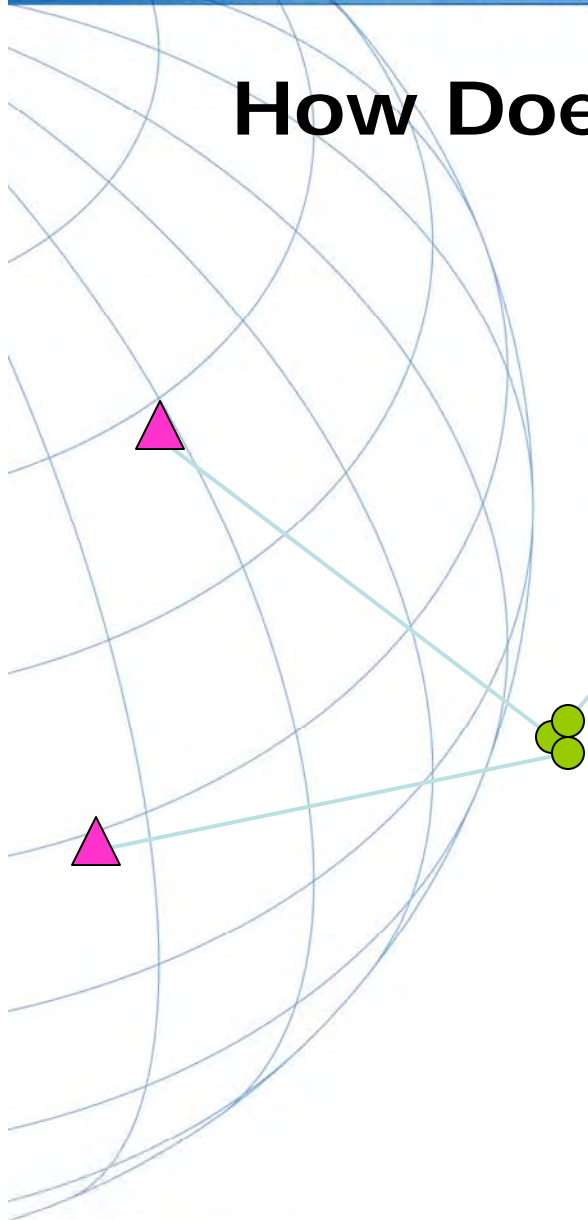


OPUS_S – Current Status

- Accepts GPS Data in
 - Native receiver format
 - RINEX format (versions 2.0 & 2.1)
- Data Processing
 - Uses three CORS stations
 - Minimum of two hours of dual-frequency data
- Provides
 - NAD83 & ITRF coordinates
 - State plane coordinates
 - UTM coordinates
 - US National grid designator
 - G-file, statistics, etc.



How Does OPUS Compute Position?



NGS-PAGES software used

L3-fixed solution w/ tropo adjusted

3 “best” CORS selected

3 separate baselines computed

3 separate positions averaged

Position differences also include any errors in CORS coordinates



Martin, Dan

From: opus [opus@ngs.noaa.gov]
Sent: Monday, December 15, 2008 2:48 PM
To: Dan.Martin@noaa.gov
Subject: OPUS solution : G056309A.08o 000489432

FILE: G056309A.08o 000489432

NGS OPUS SOLUTION REPORT

All computed coordinate accuracies are listed as peak-to-peak values. For additional information: www.ngs.noaa.gov/OPUS/Using_OPUS.html#accuracy

USER: dan.martin@noaa.gov DATE: December 15, 2008
RINEX FILE: g056309n.08o TIME: 19:48:17 UTC

SOFTWARE: page5 0810.20 master28.pl 081023 START: 2008/11/04 13:40:00
EPHEMERIS: igs15042.eph [precise] STOP: 2008/11/04 19:43:00
NAV FILE: brdc3090.08n OBS USED: 15264 / 16871 : 90%
ANT NAME: TRM55971.00 # FIXED RMS: 111 / 123 : 90%
ARP HEIGHT: 2.000 OVERALL RMS: 0.020 (m)

REF FRAME: NAD_83(CORS96) (EPOCH:2002.0000) ITRF00 (EPOCH:2008.8424)

X:	1382168.289 (m)	0.014 (m)	1382167.539 (m)	0.014 (m)
Y:	-4305939.217 (m)	0.012 (m)	-4305937.817 (m)	0.012 (m)
Z:	4482857.195 (m)	0.008 (m)	4482857.147 (m)	0.008 (m)
LAT:	44 56 28.49104	0.011 (m)	44 56 28.52569	0.011 (m)
E LON:	287 47 46.20981	0.014 (m)	287 47 46.19676	0.014 (m)
W LON:	72 12 13.79019	0.014 (m)	72 12 13.80324	0.014 (m)
EL HGT:	181.232 (m)	0.008 (m)	180.092 (m)	0.008 (m)
ORTHO HGT:	208.979 (m)	0.026 (m)	[NAVD88 (Computed using GEOID03)]	

	UTM COORDINATES	STATE PLANE COORDINATES
	UTM (Zone 18)	SPC (4400 VT)
Northing (Y) [meters]	4980227.787	271272.182
Easting (X) [meters]	720606.324	523375.038
Convergence [degrees]	1.97595564	0.20920947
Point Scale	1.00019847	0.99997100
Combined Factor	1.00017005	0.99994259

US NATIONAL GRID DESIGNATOR: 18TYQ2060680228 (NAD 83)

BASE STATIONS USED

FID	DESIGNATION	LATITUDE	LONGITUDE	DISTANCE (m)
DJ8959	VISA ST ALBANS CORS ARP	N444832.646	W0730457.289	70974.6
AF9563	VCAP VERMONT CAPITAL CORS ARP	N441543.106	W0723456.555	81247.7
DJ8955	VTD9 DERBY CORS ARP	N445703.499	W0720936.724	3610.5

	NEAREST NGS PUBLISHED CONTROL POINT	
FG1395	G 56	N445628. W0721212. 42.0

BASE STATION INFORMATION



Results not always good...Why?

OPUS solution : CP19294A.08o 000491796 - Message (Plain Text)

File Edit View Insert Format Tools Actions Help Adobe PDF

Reply Reply to All Forward

Extra line breaks in this message were removed.

From: opus [opus@ngs.noaa.gov] Sent: Thu 12/18/2008 1:34 PM
 To: Martin, Dan
 Cc:
 Subject: OPUS solution : CP19294A.08o 000491796

FILE: CP19294A.08o 000491796

NGS OPUS SOLUTION REPORT
 =====

All computed coordinate accuracies are listed as peak-to-peak values.
 For additional information: www.ngs.noaa.gov/OPUS/Using_OPUS.html#accuracy

USER: dan.martin@state.vt.us DATE: December 18, 2008
 RINEX FILE: cp19294m.08o TIME: 18:33:46 UTC

SOFTWARE: page5 0810.20 master10.p1 081023 START: 2008/10/20 12:14:00
 EPHEMERIS: igs15021.eph [precise] STOP: 2008/10/20 18:20:00
 NAV FILE: brdc2940.08n OBS USED: 13654 / 16385 : 83%
 ANT NAME: TRM55971.00 NONE # FIXED AMB: 77 / 140 : 55%
 ARP HEIGHT: 2.000 OVERALL RMS: 0.020 (m)

REF FRAME: MAD_83 (CORS96) (EPOCH:2002.0000) ITRF00 (EPOCH:2008.8023)

X:	1420019.355 (m)	0.123 (m)	1420018.606 (m)	0.123 (m)
Y:	-4299652.120 (m)	0.043 (m)	-4299650.717 (m)	0.043 (m)
Z:	4477455.321 (m)	0.118 (m)	4477455.273 (m)	0.118 (m)
LAT:	44 52 13.26549	0.087 (m)	44 52 13.30020	0.087 (m)
E LON:	288 16 35.46496	0.117 (m)	288 16 35.45261	0.117 (m)
W LON:	71 43 24.53504	0.117 (m)	71 43 24.54739	0.117 (m)
EL HGT:	434.235 (m)	0.103 (m)	433.090 (m)	0.103 (m)
ORTHO HGT:	461.569 (m)	0.106 (m)	[NAVD88 (Computed using GEOID03)]	

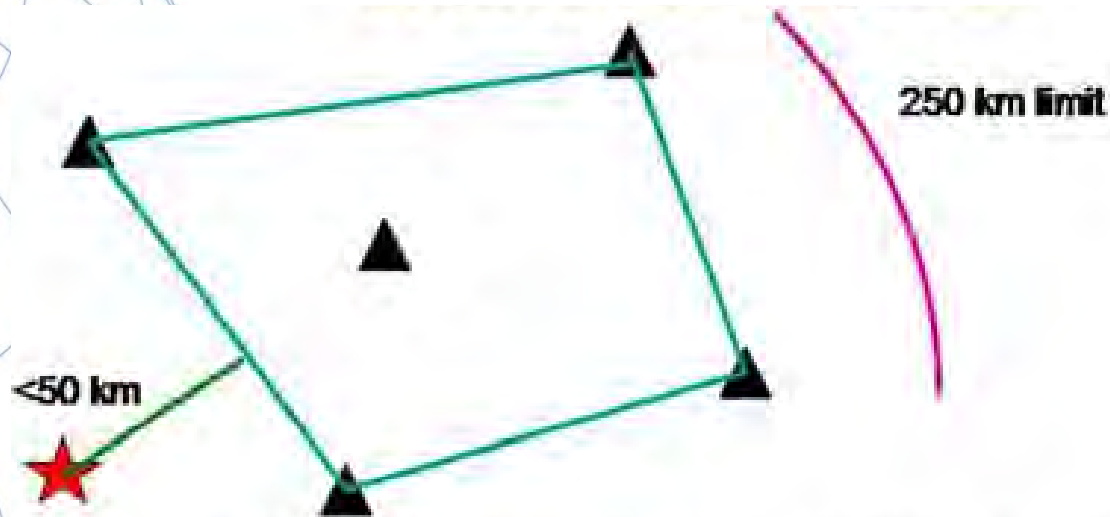


OPUS-Rapid Static (OPUS-RS)

- 15-minute to 4-hour sessions
- ties to 3 – 9 CORS (< 250km)
- uses RSGPS vs. PAGES software
- P1/P2 code & L1/L2 phase observations
- resolves all ambiguities with LAMBDA (Least Squares Ambiguity Decorrelation Adjustment)
- similar to Real-Time Network computations
- RSGPS solution modes:
 - network: solves ambiguities, tropo, iono
 - rover: tropo and ion interpolated to rover
- ~10,000 lines of code



OPUS-RS Reference Station Search Algorithm



- Sort stations in CORS network by distance from rover. Select up to nine CORS that are less than 250 km from rover, with suitable data.
- No solution is attempted if fewer than three CORS selected.
- No solution attempted if distance from rover to polygon enclosing selected CORS is greater than 50 km.

OPUS-RS Output

NGS OPUS-RS SOLUTION REPORT

USER:	william.stone@noaa.gov	DATE:	October 29, 2007
RINEX FILE:	1207287x.07o	TIME:	14:39:04 UTC
SOFTWARE:	rsgps 1.09 RS11.prl 1.12	START:	2007/10/14 23:27:15
EPHEMERIS:	igr14490.eph [rapid]	STOP:	2007/10/15 00:00:15
NAV FILE:	brdc2870.07n	OBS USED:	1962 / 2082 : 94%
ANT NAME:	ASH701975.01A	QUALITY IND.	34.21 / 37.91 *
ARP HEIGHT:	0.0	NORMALIZED RMS:	0.307
REF FRAME:	NAD_83(CORS96)(EPOCH:2002.0000)	ITRF00 (EPOCH:2007.78627)	
LAT:	36 2 52.79767 0.008(m)	36 2 52.81498 0.008(m)	
E LON:	252 2 18.45532 0.013(m)	252 2 18.41156 0.013(m)	
W LON:	107 57 41.54468 0.013(m)	107 57 41.58844 0.013(m)	
EL HGT:	1974.304(m) 0.005(m)	1973.396(m) 0.005(m)	
ORTHO HGT:	1995.280(m) 0.026(m)	[Geoid03 NAVD88]	

"#Fixed Ambiguities" replaced by "Quality Indicator"

- average of W-ratio (separation between candidate sets of ambiguities) of last 3 epochs
- reported as network mode / rover mode
- look for values > 3 for confidence in solution

OPUS-RS Output

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EPHEMERIS:	igr14490.eph [rapid]	STOP:	2007/10/15 00:00:15
NAV FILE:	brdc2870.07n	OBS USED:	1962 / 2082 : 94% ANT
NAME:	ASH701975.01A	QUALITY IND.	34.21 / 37.91
ARP HEIGHT:	0.0	NORMALIZED RMS:	0.307 *
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"Overall RMS" replaced by "Normalized RMS"

- unitless quantity, "expected" = 1
- aka standard deviation of unit weight
- if > 1 , noisy data somewhere
- typically < 1 , meaning noise less than expected



OPUS-RS Output

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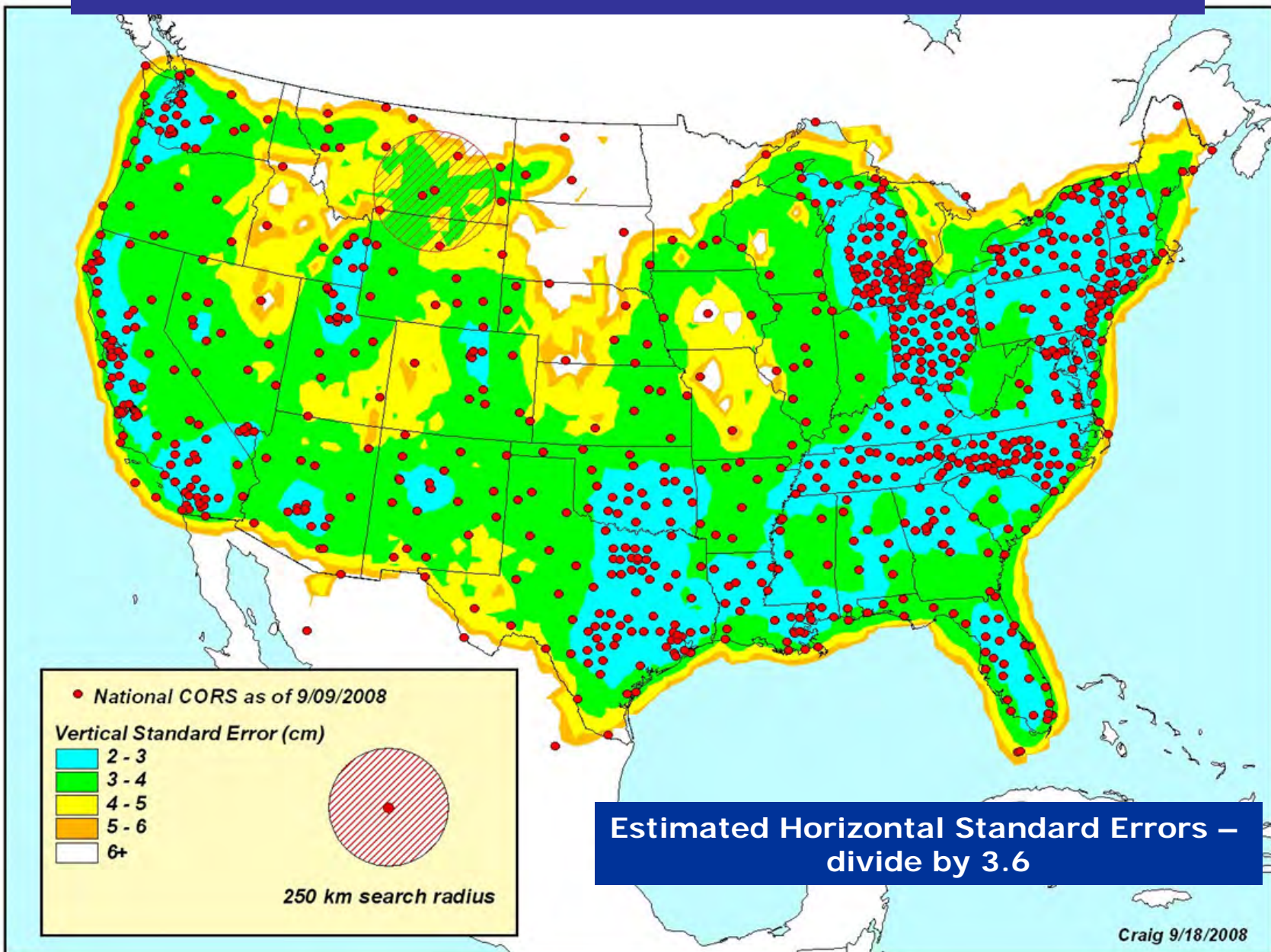
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Peak-to-Peak replaced by Est. Standard Deviations

- approximately 95% confidence
- derived from scatter of single baseline solutions
- formal standard deviations (optimistic) available in Extended Output



Estimated Vertical Standard Errors – f(IDOP & RMSD) 15-Minute OPUS-RS Sessions



OPUS_DB

- Uses OPUS processor
- Minimum of 4 hours of dual frequency data
- If criteria is met mark can be published > 4 hour duration
 - > 70% observations used
 - > 70% ambiguities fixed
 - < 0.04m horizontal peak-to-peak (VT 0.03)
 - < 0.08m vertical peak-to-peak (VT 0.055)
 - < 0.03m RMS
 - IGS precise or rapid orbits (available next day)
- **metadata:**
 - quality [survey mark](#)
 - photos of mark & equipment
 - mark details (name, type, stability)
 - description to aid mark recovery





OPUS: Online Positioning User Service

upload

view

about

compute an accurate position for your GPS data file

1. enter your [email address](#)

2. attach your [DATA file](#)

3. select your [antenna type](#)

4. add your [antenna height](#)

meters

5a. customize your solution, report, and publishing [options](#)

-or-

5b. choose a [processor](#)

for L1/L2 GPS data > 15 min. < 2 hrs.

for L1/L2 GPS data > 2 hrs. < 48 hrs.



OPUS - Options - Windows Internet Explorer

http://beta.ngs.noaa.gov/OPUS/options.html

File Edit View Favorites Tools Help

msn Powered by Live Search Search News Entertainment Video 53°F

OPUS - Options

Project Name

6. Set User Profile

OPUS allows the antenna type, antenna height, SPC code, selected base stations and extended option choices that you have just identified to be assigned to the email address that you have entered. These entries & selections will be saved and used for your subsequent OPUS submissions, saving time for multiple or repetitive submissions using the same equipment and options configuration. When your profile is set, you will only need to enter your email address and your data file and then upload. Your profile will automatically supply the saved entries. When your data is finished uploading, the upload page will display your profile entries.

To change and reset your profile, complete all the main page entries to gain access again to the options page. You may also elect to delete your profile. (Hint: You might use different email aliases to identify different equipment and processing configurations that you frequently use.)

Set/Reset my profile. Delete my profile.

7. Submit to Data Base

OPUS allows qualified users to submit results for publication in the NGS Data Base.

Yes, publish. No, don't publish.

[Information](#) on the National and Cooperative CORS sites

Done Internet 100%



Martin, Dan

From: opus [opus@ngs.noaa.gov]
 Sent: Monday, December 15, 2008 2:48 PM
 To: Dan.Martin@noaa.gov
 Subject: OPUS solution : G056309A.08o 000489432

FILE: G056309A.08o 000489432

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Point Scale	1.00019847	0.99997100
Combined Factor	1.00017005	0.99994259

US NATIONAL GRID DESIGNATOR: 18TYQ2060680228 (NAD 83)

BASE STATIONS USED

FID	DESIGNATION	LATITUDE	LONGITUDE	DISTANCE (m)
DJ8959	VISA ST ALBANS CORS ARP	N444832.646	W0730457.289	70974.6
AF9563	VCAP VERMONT CAPITAL CORS ARP	N441543.106	W0723456.555	81247.7
DJ8955	VTD9 DERBY CORS ARP	N445703.499	W0720936.724	3610.5

NEAREST NGS PUBLISHED CONTROL POINT			
FG1395	G 56	N445628.	W0721212.
			42.0

BASE STATION INFORMATION





Step 2 of 4: Identify your Mark



An OPUS solution report is now being prepared. When complete, it will be e-mailed to you.

PUBLISHING

* Confused? [New and recovered marks are described here.](#)

OPUS ENTRIES

e-mail address: dan.martin@noaa.gov

Selected Antenna: TRM55971.00

Uploaded File Name: 5600326A.08o

Antenna Height(m): 2.000

OPTIONS

State Plane Code: **AUTO**

User Selected Base Stations: **NONE**

Extended Output: **YES**

User Excluded Stations: **NONE**

Submit to NGS Database: **YES**

User Selected Project Name: **NONE**





Step 3 of 4: Describe Recovered Mark

for data file: g056309n.08o



R
E
Q
U
I
R
E
D

Enter the mark's **PID**: | [Find PID](#) | [no PID ?](#) |

Close-up photo:

Horizon photo:

O
P
T
I
O
N
A
L

Mark Condition Good condition
 Poor, disturbed, mutilated, requires maintenance

Descriptions

(Amend existing description, if necessary. Max. characters=500)

Privacy Policy: All data you voluntarily provide here will be shared publicly on datasheets ([example](#)). See also our [NOAA Privacy Policy](#).





Step 2 of 4: Identify your Mark



An OPUS solution report is now being prepared. When complete, it will be e-mailed to you.

PUBLISHING

Describe New* Mark

Describe Recovered* Mark

Abort

* Confused? [New and recovered marks are described here.](#)

OPUS ENTRIES

e-mail address: dan.martin@noaa.gov

Selected Antenna: TRM55971.00

Uploaded File Name: 5600326A.08o

Antenna Height(m): 2.000

OPTIONS

State Plane Code: **AUTO**

User Selected Base Stations: **NONE**

Extended Output: **YES**

User Excluded Stations: **NONE**

Submit to NGS Database: **YES**

User Selected Project Name: **NONE**





Step 3 of 4: Describe New Mark

for data file: 5600326o.08o



REQUIRED

Designation:

Stamping :

Type:

IF Type = "Rod": **Rod Depth** **Sleeve Depth**

Setting:

specific setting:

Descriptions :

(describe the mark, witness ties, etc., to enable future recoveries. Max. characters=500)

Close-up photo:

Horizon photo:

OPTIONAL

Stability:

Magnetic:

Application:



Dan.Martin@noaa.gov: Inbox



Compose Reply Reply All Forward Delete Printable Add Addresses Previous Next Close

From opus <opus@ngs.noaa.gov>

Sent Monday, December 15, 2008 3:05 pm

To Dan.Martin@noaa.gov

Subject OPUS Recovery Mark: RINEX FILE: g056309n.08o.gz, DESIGNATION: G 56

The following contribution has been submitted to OPUS for publication in the OPUS Database. Please visit the link below to verify that the information you provided is correctly presented on the new datasheet.

When the datasheet is viewed, two buttons will be displayed at the top of the new datasheet web page. Please select the appropriate button to accept or withdraw your contribution. An action must be taken for the datasheet to be published or withdrawn.

The OPUS Team.

RINEX FILE: g056309n.08o.gz

DESIGNATION: G 56

<http://beta.ngs.noaa.gov/OPUS/getFeedback.jsp?id=000489432>



Almost Done



MHTML Document



The screenshot shows a Windows Internet Explorer browser window titled "feedbackAction - Windows Internet Explorer". The address bar contains the URL "http://beta.ngs.noaa.gov/OPUS/feedbackAction.jsp?status=approve". The browser's menu bar includes "File", "Edit", "View", "Favorites", "Tools", and "Help". The toolbar shows "Convert" and "Select" buttons. The address bar also includes a "Live Search" field. The main content area displays the following text:

*You approved the datasheet. Thanks for sharing your data with NGS.
Your datasheet is now publishable subject to review by NGS. If you wish to reconsider your decision,
please contact NGS immediately at NGS.Opus_db@noaa.gov*

The status bar at the bottom of the browser window shows "Done", "Internet", and "100%" zoom level.



Sun Java™ System Messenger Express Welcome Dan Martin

Folders **Inbox** Sent Trash Drafts Addresses Options

Dan.Martin@noaa.gov: Inbox

Compose Reply Reply All Forward Delete Printable Add Addresses Previous Next Close

From NGS.Opus_db@noaa.gov

Sent Tuesday, December 16, 2008 12:47 pm

To NGS.Opus_db@noaa.gov , Dan.Martin@noaa.gov

Subject Opus submission(ID=000489432)

Submitter dan.martin@noaa.gov approved the datasheet for ID=000489432



OPUS-Projects

- Managers can define a project
 - Process any number of stations under a project
 - Project can span several days to weeks
 - Contract work
- Project processing
 - Each dataset sent to OPUS but identified with a project
 - Results returned to submitter a few minutes later
 - Manager can monitor processing and submission
- Final adjustment
 - Entire project adjusted as one campaign
 - Review & submission to NGS

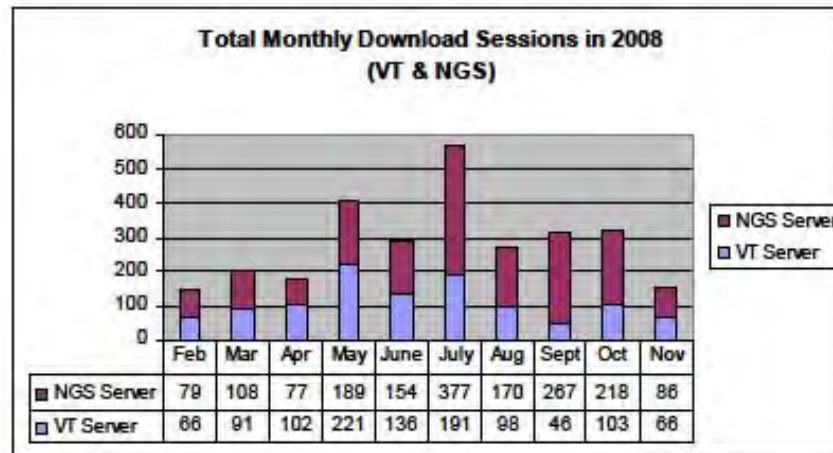
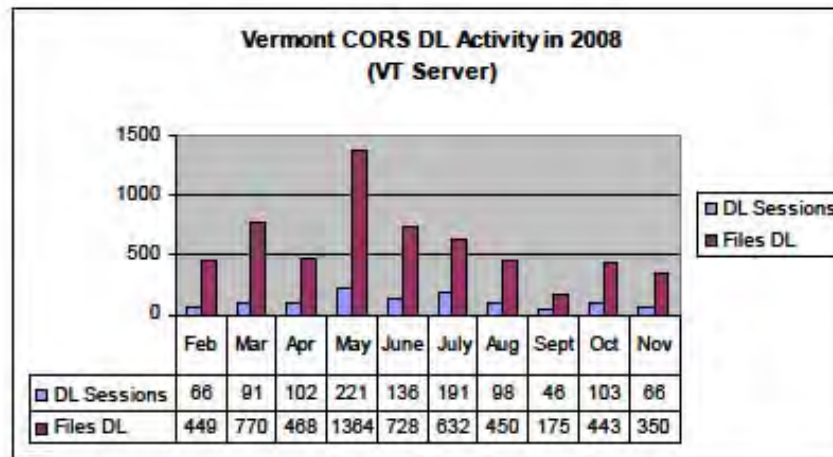


OPUS Mapper

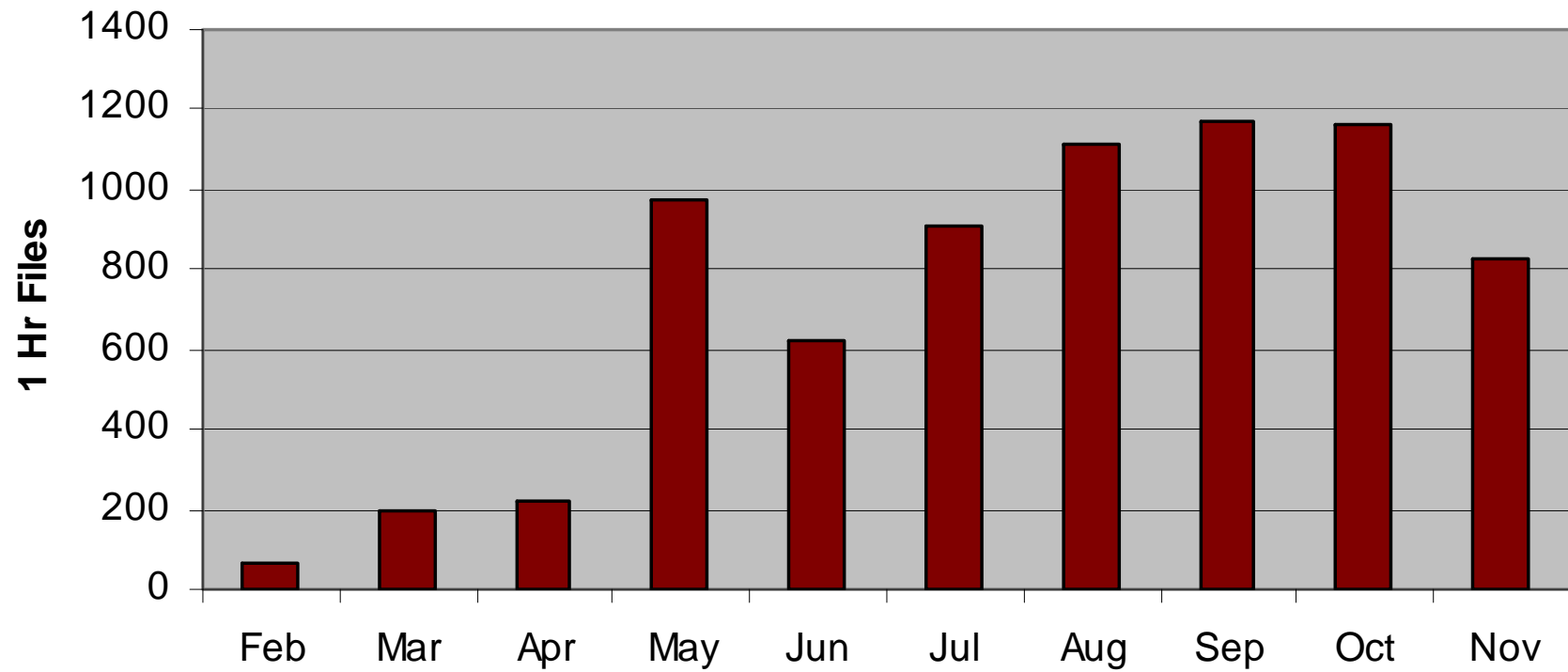
- Compute a differential pseudo range solution for less expensive GPS receivers
- Aimed at the GIS community who do not require cm level accuracies
- Allows processing in a consistent approach and “certify” their locations in the NSRS
- Generate rapid static solution from seconds or minutes of data
- Accuracies: A few decimeters to a meter horizontally



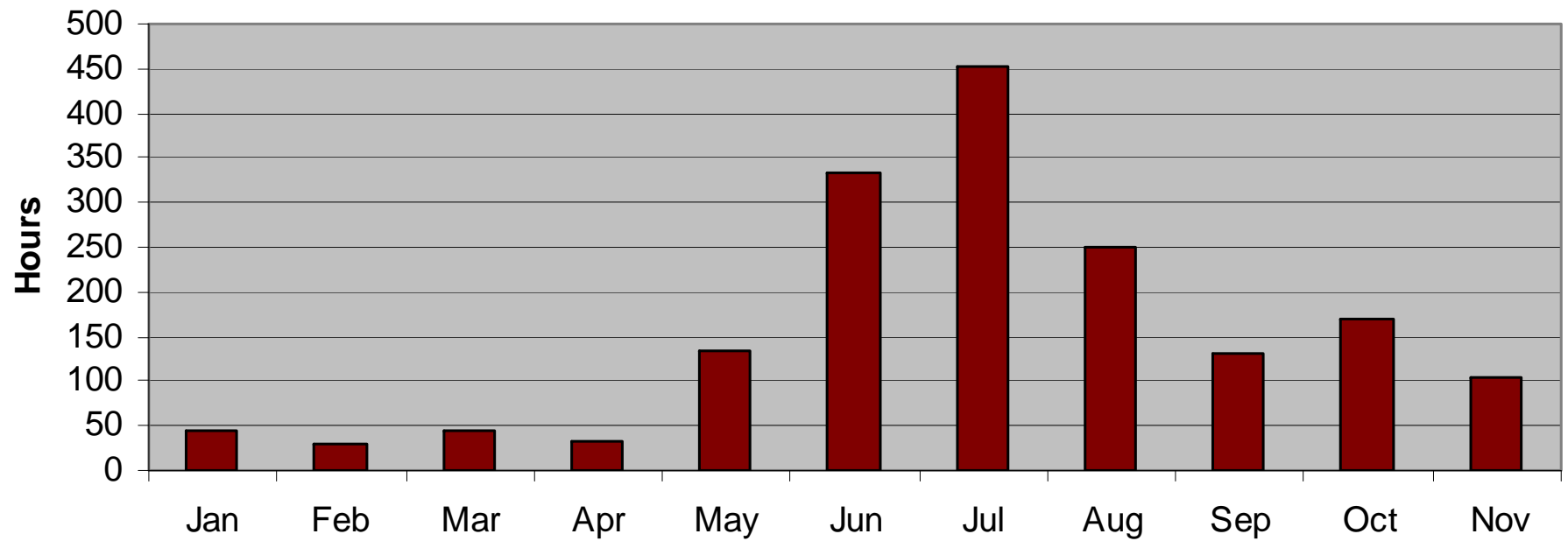
VT CORS Downloads for 2008



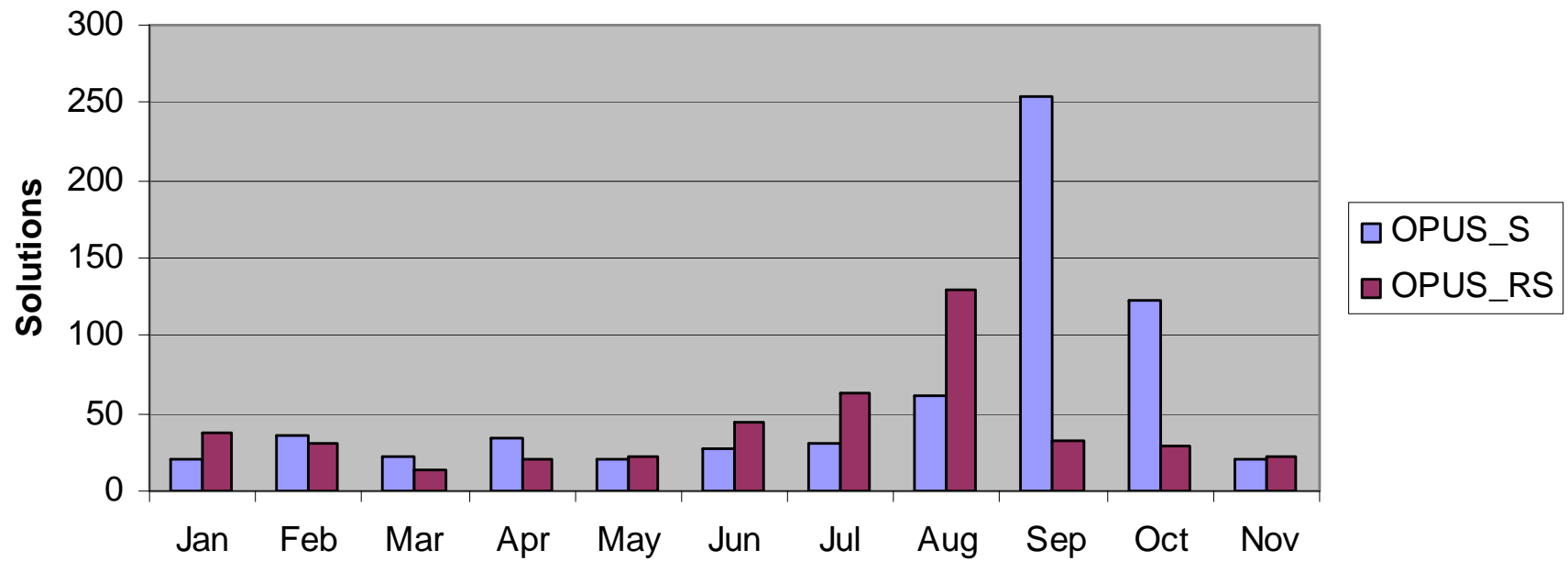
VT FTP Downloads in 2008



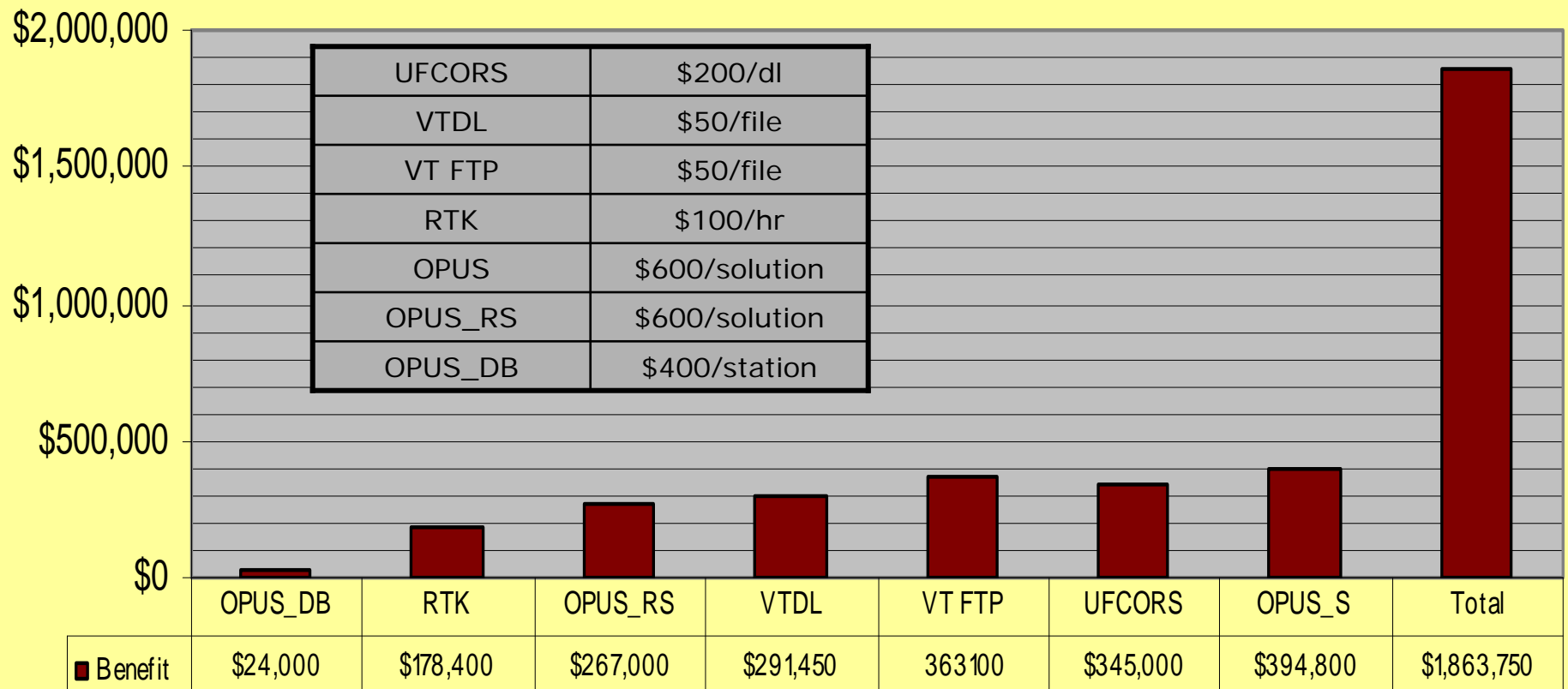
Real Time Use in 2008



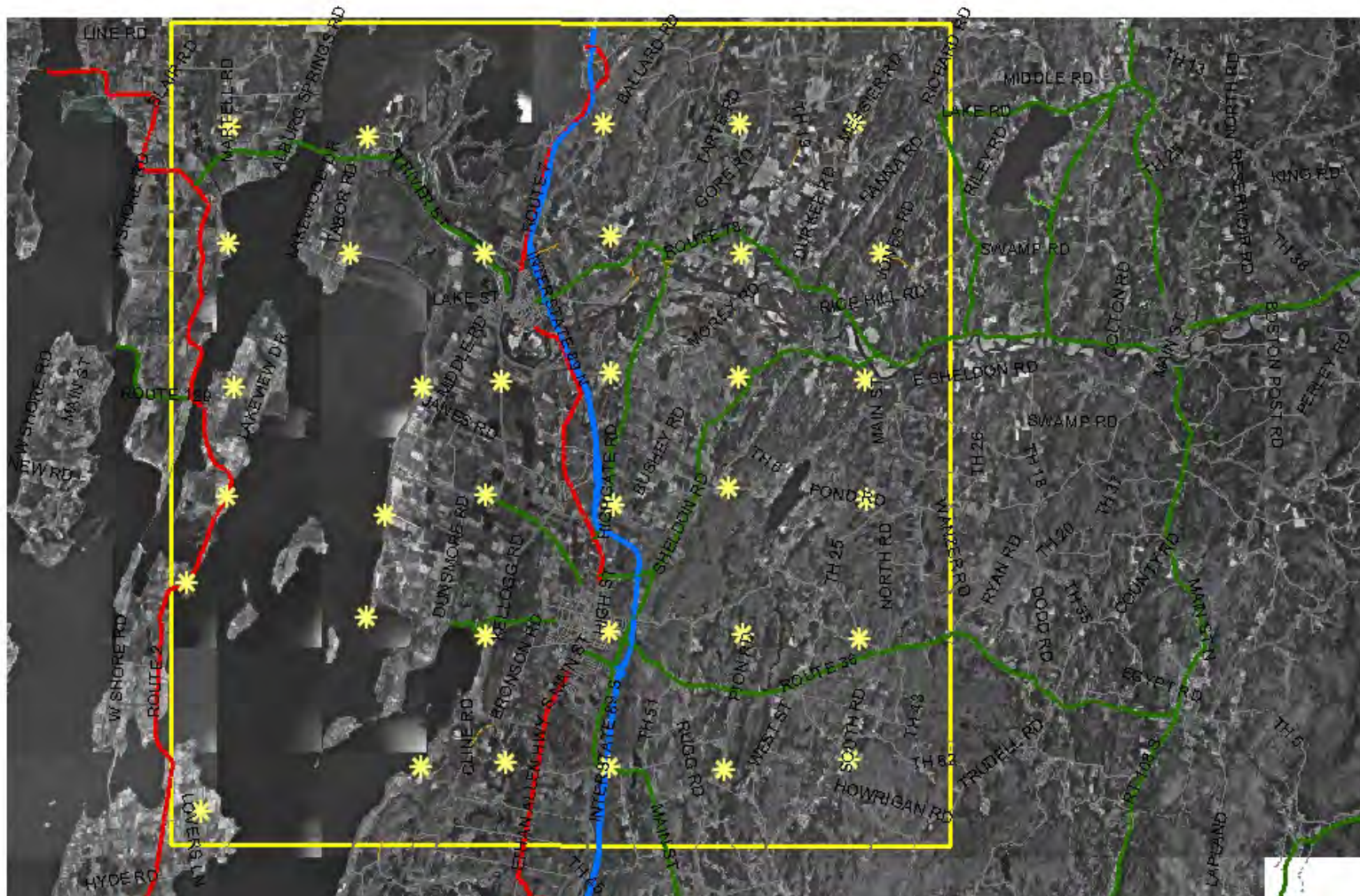
OPUS Usage in 2008



2008 Benefits of VT CORS as of Nov. 30

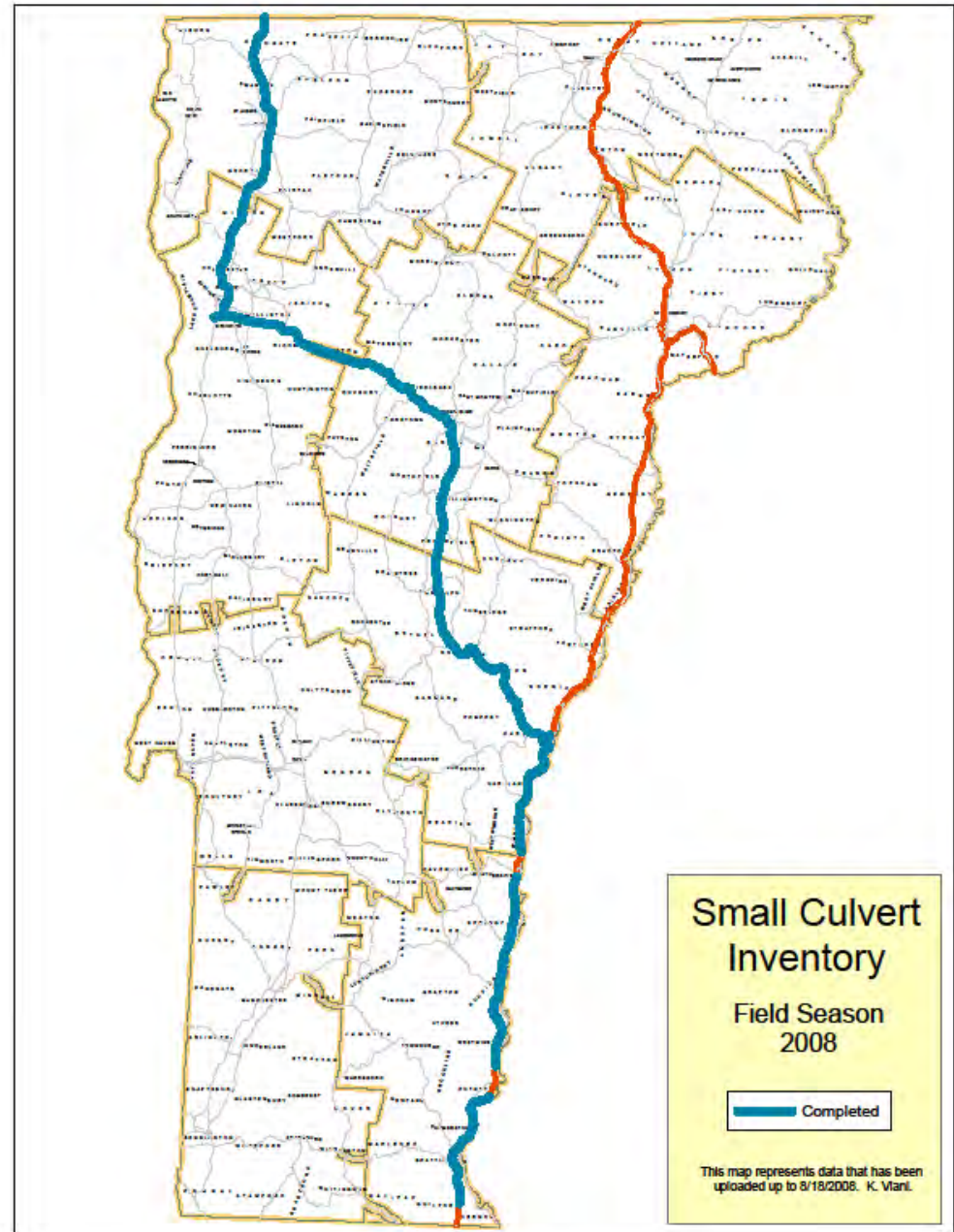


QA/QC for LiDAR (Real-time)



Interstate Small Culvert Inventory 2007-2008

- 189
 - ≈4000 Culverts
 - ≈2800 DI's
 - ≈10,800 Total Shots
- 191 (first 95 miles)
 - ≈2700 Culverts
 - ????? DI's
 - ≈5400 Total Shots+DI's
- 59 crew weeks
 - ≈ \$60k savings



189 Small Culvert Inventory



National Geodetic Survey

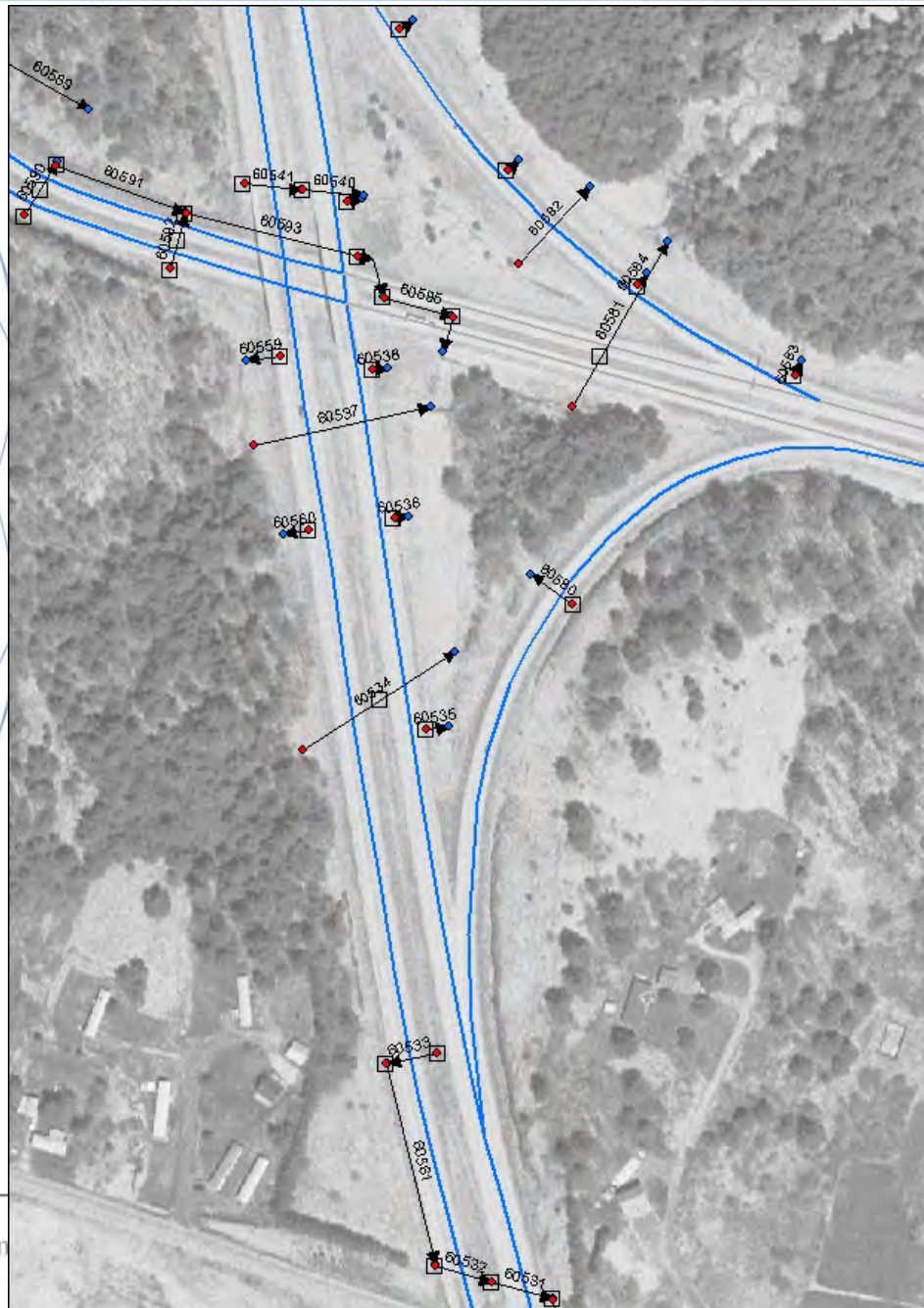
The screenshot shows the ArcMap interface with the following components:

- Title Bar:** small_culv - ArcMap - ArcView
- Menu Bar:** File Edit View Insert Selection Tools Window Help
- Toolbars:** Standard toolbar, Editor toolbar (Task: Create New Feature), and a secondary toolbar with various navigation and editing tools.
- Layers Panel:** A list of layers including Outlet, Inlet, PntPosn, and Orthophotos (with sub-layers like addison, bennington, etc.).
- Identify Results Dialog:** A window titled 'Identify Results' showing the following data for the selected feature (ID 10199):

Field	Value
FID	25
Shape	Point
PID	50092
Drain_Type	CCROSS
Struc_Type	RND
Material	CONC
Size	18
Other_Widht	0
Other_Heig	0
Out_Treatm	DI
Depth_Fill	10
Modificati	NONE
Outlet_Tie	NO
Marker_Pos	NO
Inspector	KViani
Out_Cond	GOOD
Pipe_Cond	UNKNW
Stone_Pad	NA
Sediment	LIGHT
Rd_Setlin	NONE
Sink_Holes	NONE
Erosion	NONE
Piping	NO
Comments	
Point_Name	10199
Date_Obs	9/13/2007
Elev_Obs	87.912
H_Prec_Obs	0.008
V_Prec_Obs	0.013
- Status Bar:** 446432.88 222082.18 Unknowl
- Taskbar:** Windows Start button, taskbar with 'Presentations', 'Microsoft Power...', and 'small_culv - Arc...' open. System tray shows the time as 9:28 AM.



National Geodetic Survey



National Oceanic and Atmospheric Administration

Other Uses – Jason Dattilio, L.S., Button Professional Land Surveyors

“As you are aware GPS surveying is the State of Vermont has come a long way in the decade. I can remember when Montpelier was the only CORS Station available, now we are well on our way to having a network of coverage across the entire state. Gone are the days of the back pack systems and utilizing survey grade equipment only to run control networks or place a project on Vermont State Plane.”

“Currently at Button Professional Land Surveyors we’re utilizing our Trimble R8 GPS System almost on a daily basis...”

“Many advantages can be provided by having a survey grade GPS system. They will allow you to be more creative, and in most cases more efficient. Checking your GPS work is critical, but with the proper downloading and processing procedures you will feel confident that your work was collected properly. Feeling comfortable with ;your work may take a while, but certainly this is not uncommon with surveyors or with anyone using something that is new.”



BPLS Applications

- Establishing Control
- Tying out Random Trav.
- Elevations for Flood Cert.
- Topo to generate surfaces
- Locate boundary evidence
- Locate wetlands
- Establish True North on tower site surveys
- Horizontal and vertical construction layout
- Setting Property Corners
- Searching for control
- Static Observations
- Forensic surveys
- As-built surveys



BPLS Notes On Procedures and Usability

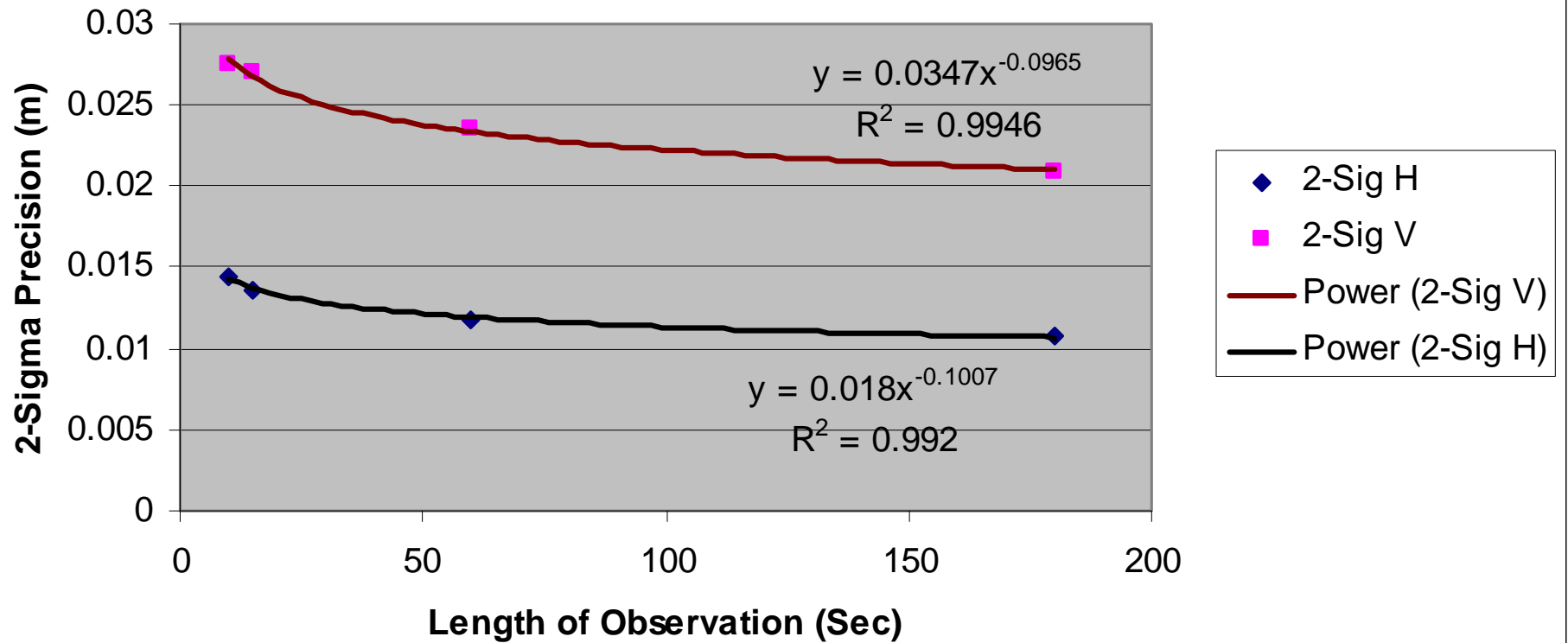
- Build in redundancy for important points
 - Second shot taken with different initialization and new tripod setup (rotated)
 - View residuals, and field average if within tolerances (0.03') (0.03'-0.06' typical)
 - Topo pts. for 5 sec., control and property corners for 15 sec.
- Field calibrations used when called for. Always check into other points (H&V) to verify calibration
- Using CORS and Geoid for positions, try to verify by checking into known NSRS control if possible.



2 Sigma Horizontal and Vertical Precisions vs. Time

Horizontal Coefficient of Correlation = 0.899

Vertical Coefficient of Correlation = 0.947



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- [CORS Presentation - January 24, 2008 Maine Society of Land Surveyors](#)
- [NGS Activities and Initiatives - January 25, 2008 Maine society of Land Surveyors](#)
- [VT RTK Case Study - March 07, 2008 American Congress on Surveying and Mapping](#)
- [VT State Plane - April 11, 2008 Vermont Society of Land Surveyors](#)

Questions/Discussion

- Should VT surveying standards include provisions utilizing GPS methodologies?
- What about reporting/documentation?
- Is it time to consider non-relative or "CORS relative" accuracy standards? What positional error for 1:20,000 when positioning from 20km (12.5mi)?
- What are the issues when mixing networks?
- What are the issues when mixing methods?
- What are the real benefits to the surveyor?
- Are there benefits to using dual constellation receivers?
- Are there real benefits or is it just another way to skin the cat?

